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On the product combination of logharmonic mappings

In this paper, we consider the class of logharmonic mappings defined on the unit disc U . A local and global representation will be given. Topics will be included, mapping theorems, logharmonic automorphisms, univalent starlike logharmonic mappings. We obtain some sufficient conditions for the product combination of univalent logharmonic mappings to be starlike. A number of explanatory examples are included.

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Marcin Adam

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Stability of the polynomial functional equation in the class of differentiable functions

During the 15th International Conference on Functional Equations and Inequalities (Ustroń, May 19–25, 2013) we have shown that the class $C^p(\mathbb{R}, \mathbb{R})$ of p -times continuously differentiable functions has the difference property of p -th order, i.e. if a function $f: \mathbb{R} \rightarrow \mathbb{R}$ is such that $\Delta_h^p f \in C^p(\mathbb{R} \times \mathbb{R}, \mathbb{R})$, where $\Delta_h^p f$ is the p -th iterate of the difference operator $\Delta_h f(x) := f(x+h) - f(x)$, then there exists a unique polynomial function $P: \mathbb{R} \rightarrow \mathbb{R}$ of

$(p - 1)$ -th order such that $f - P \in C^p(\mathbb{R}, \mathbb{R})$. Inspired by some results concerning the stability of the Cauchy functional equation (see [1]), as an application of our previous theorem we will present some stability result for the polynomial functional equation in the class of differentiable functions.

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Pekka Alestalo

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Hyers-Ulam theorem for bounded sets and applications

We present a version of the Hyers-Ulam theorem for bounded sets [1]. The result states that for $A \subset \mathbb{R}^n$ bounded, an ε -nearisometry $f: A \rightarrow \mathbb{R}^n$ can always be approximated by an isometry in such a way that the error term is proportional to $\sqrt{\varepsilon}$, and in many cases even to ε .

These results are then applied to prove extension theorems for $(1 + \varepsilon)$ -bilipschitz maps $f: A \rightarrow \mathbb{R}^n$, [2, 3], and more generally, for the so-called power-quasisymmetric maps, [4, 5].

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Szilárd András

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(joint work with **Árpád Baricz** and **Tibor Pogány**)

Ulam-Hyers stability of integral equations with weak singularities

The main aim of our talk is to study the Ulam-Hyers stability of some singular integral equations by using fixed point techniques and the theory of Picard operators. Our methods can be used both on timescales for dynamic equations and for integral equations on a half-line. We apply the same methods to study the Ulam-Hyers stability of the Bessel differential equation and to the hypergeometric differential equation.

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Roman Badora

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Invariant means in the theory of stability

Let $(S, +)$ be a semigroup. For a function f on S with values in a set Y and $a \in S$ the left and the right translations ${}_a f$ and f_a be defined by the following formulae

$${}_a f(x) = f(a + x), \quad f_a(x) = f(x + a), \quad x \in S.$$

A real linear functional M defined on the space $B(S, \mathbb{R})$ of all real bounded functions on S is called a *left (right) invariant mean* if and only if it satisfies the following conditions:

$$\inf_{x \in S} f(x) \leq M(f) \leq \sup_{x \in S} f(x)$$

and

$$M({}_a f) = M(f) \quad (M(f_a) = M(f))$$

for all $f \in B(S, \mathbb{R})$ and $a \in S$.

A semigroup S which admits a left (right) invariant mean on the space $B(S, \mathbb{R})$ will be termed *left (right) amenable*.

The classical result on invariant means (J. von Neumann, J. Dixmier, M.M. Day) states that every commutative semigroup is amenable.

L. Székelyhidi, in 1985, for the first time applied the method of invariant means in the theory of functional equations (L. Székelyhidi, *Remark 17*, Report of Meeting, Aequationes Math. **29** (1985), 95–96). From this time, using the method of invariant means, many interesting results concerning functional equations and inequalities were proved.

In the talk we present applications of invariant means in the stability theory of functional equations.

Anna Bahyrycz

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(joint work with **Jolanta Olko**)

On hyperstability of the general linear equation

We consider the functional equation

$$\sum_{i=1}^m A_i g\left(\sum_{j=1}^n a_{ij} x_j\right) + A = 0, \quad (1)$$

with $A, a_{ij} \in \mathbb{F}$, $A_i \in \mathbb{F} \setminus \{0\}$, $i \in \{1, \dots, m\}$, $j \in \{1, \dots, n\}$ for functions g mapping a normed space into a normed space (both over the field $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$).

We present a result on hyperstability of the equation (1) and applying it we obtain sufficient condition for the hyperstability of the wide class of functional equations and control functions.

We also show how our outcome may be used to check if the particular functional equation is hyperstable.

Bogdan Batko

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Superstability of some conditional functional equations

We present some superstability results, in the sense of Baker, of selected conditional functional equations with the condition dependent on an unknown function.

Zoltán Boros

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(joint work with **Noémi Nagy**)

Rolewicz theorem for convexity of higher order

Let $I \subset \mathbb{R}$ be an open interval. Rolewicz [2] investigated functions $f: I \rightarrow \mathbb{R}$ that satisfy inequalities of the form

$$f(tx + (1-t)y) \leq tf(x) + (1-t)f(y) + Ct(1-t)\alpha(|x-y|) \quad (1)$$

for every $x, y \in I$, $t \in [0, 1]$, with a non-negative constant C and a nondecreasing function $\alpha: [0, +\infty[\rightarrow [0, +\infty[$ fulfilling $\lim_{t \rightarrow 0+} \frac{\alpha(t)}{t^2} = 0$. He proved that every continuous solution f of inequality (1) has to be convex.

Following Hopf's theses (Berlin, 1926) and Popoviciu's monograph [1], a function $f: I \rightarrow \mathbb{R}$ is called convex of order n if

$$[x_0, x_1, \dots, x_n, x_{n+1}; f] \geq 0$$

for all $x_0 < x_1 < \dots < x_n < x_{n+1}$ in I , where $[x_0, x_1, \dots, x_n, x_{n+1}; f]$ denotes the divided difference of f at the points $x_0, x_1, \dots, x_n, x_{n+1}$.

As a generalized and higher order version of Rolewicz's theorem, we establish the following result.

THEOREM

Let $n \in \mathbb{N}$, $\nu(I)$ denote the length of the interval I , and $J_I =]0, \nu(I)[$. Let the function $\varphi: J_I \rightarrow [0, +\infty[$ satisfy $\lim_{t \rightarrow 0^+} \varphi(t) = 0$. If a function $f: I \rightarrow \mathbb{R}$ satisfies the inequality

$$[x_0, x_1, \dots, x_n, x_{n+1}; f] + \varphi(x_{n+1} - x_0) \geq 0$$

for all $x_0 < x_1 < \dots < x_n < x_{n+1}$ in I , then f is convex of order n .

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Janusz Brzdęk

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(joint work with **Liviu Cădariu**)

On stability of a family of functional equations

We present some general stability (and hyperstability) results for the functional equation of the following form

$$f(px + r_1y) + f(qx + r_2y) = f(x) + \sum_{i=1}^m \alpha_i f(s_iy) + D(x, y), \quad (1)$$

in the class of functions f mapping a commutative group $(X, +)$ into a Banach space Y (over a field \mathbb{F} of real or complex numbers), where the function $D: X^2 \rightarrow Y$ is given, $m \in \mathbb{N}$, $\alpha_1, \dots, \alpha_m \in \mathbb{F}$ and $p, q, r_1, r_2, s_1, \dots, s_m$ are fixed endomorphisms of X .

We also provide some applications of those outcomes for characterizations of inner product spaces and stability of $*$ -homomorphisms of C^* -algebras.

The main result has been obtained by a fixed point method.

Liviu Cădariu

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Fixed point theory and the Hyers-Ulam stability of functional equations

The fixed point method is one of the most popular technique extensively used for proving properties of Hyers-Ulam stability of several functional equations. A lot of authors follow the approaches from [2] and [5] and make use of a theorem of Diaz and Margolis.

The aim of this talk is to present applications of some fixed point theorems to the theory of Hyers-Ulam stability for several functional equations.

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Jacek Chmieliński

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Orthogonality equations and their stability

Some stability aspects of the *orthogonality equation*

$$\langle f(x)|f(y) \rangle = \langle x|y \rangle, \quad x, y \in X$$

and its “pexiderization”

$$\langle f(x)|g(y) \rangle = \langle x|y \rangle, \quad x, y \in X$$

will be considered. Here X, Y are inner product spaces and $f, g: X \rightarrow Y$ unknown functions. As for the former equation, the results are surveyed, e.g., in [1].

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Jacek Chudziak

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Stability problem for composite type functional equations

Composite type functional equations play a significant role in various branches of mathematics and they have several interesting applications. Therefore there is an objective need of considering their stability properties. The main difficulty in such studies is caused by the fact that the classical methods of stability theory are, in general, useless in the case of the composite equations.

In this talk we discuss various aspects of the stability problem for the Gołąb-Schinzel equation

$$f(x + f(x)y) = f(x)f(y)$$

and its further generalizations. Moreover we present some results concerning approximate dynamical systems on interval. This problem is closely related to stability of the translation equation.

Krzysztof Ciepliński

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On a functional equation characterizing multi-additive mappings and its Hyers-Ulam stability

Let us recall that a function $f: V^n \rightarrow W$, where V is a commutative semigroup, W is a linear space and n is a positive integer, is called *multi-additive* or *n-additive* if it is additive (satisfies Cauchy's functional equation) in each variable.

In the talk, we give a functional equation which characterizes multi-additive mappings. Moreover, we present some results on the generalized Hyers-Ulam stability of this equation in normed, non-Archimedean normed and 2-normed spaces.

Marek Czerni

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Set stability of Shanholt type for linear functional equations

G.A. Shanholt gave in his paper [1] the definition of stability of closed sets in finite dimensional normed space in relation to solutions of difference equation.

In this talk we consider stability of Shanholt type of normal regions on the plane with respect to the family of continuous solutions of the linear functional equation of the form

$$\varphi[f(x)] = g(x)\varphi(x) + h(x) \tag{1}$$

with the unknown function φ .

The given functions f , g and h will be subjected to the following conditions:

(H_1) The function f is strictly increasing, continuous mapping from interval $(0, a)$, $0 < a \leq \infty$ onto itself and $0 < f(x) < x$ for $x \in (0, a)$.

(H_2) The function g is defined and continuous on the interval $(0, a)$ and $g(x) > 0$ for $x \in (0, a)$.

(H_3) The function h is defined and continuous on the interval $(0, a)$.

It is known that if the given functions f , g and h fulfill hypotheses (H_1) – (H_3), then the continuous solutions of equation (1) depend on an arbitrary function.

We shall consider also a particular case of this type of stability and show that such a stability implies the stability in the sense of Hyers-Ulam of equation (1) in some special class of functions.

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Jana Dvořáková

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Chaos in nonautonomous discrete dynamical systems

We consider nonautonomous discrete dynamical systems $(I, f_{1,\infty})$ given by sequences $\{f_n\}_{n \geq 1}$ of surjective continuous maps $f_n: I \rightarrow I$ converging uniformly to a map $f: I \rightarrow I$ and study some aspects of chaotic behavior of such systems. Recently it was proved, among others, that generally there is no connection between chaotic behavior of $(I, f_{1,\infty})$ and chaotic behavior of the limit function f . We show that even the full Lebesgue measure of a distributionally scrambled set of the nonautonomous system does not guarantee the existence of distributional chaos of the limit map and conversely, that there is a nonautonomous system with arbitrarily small distributionally scrambled set that converges to a map distributionally chaotic a.e.

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An approach to the stability of fractional differential equations

Let D^α be the Caputa fractional derivative, $\beta > 0$, $f: J \times C([-h, 0], \mathbb{R}) \rightarrow \mathbb{R}$, ($J = [t_0, \infty)$), be a given function satisfying some assumptions that will be specified, $h > 0$ and $\phi \in C([t_0 - h, t_0], \mathbb{R})$. Consider the following fractional differential equation

$$\begin{aligned} D^\alpha[y(t)e^{\beta t}] &= f(t, y(t))e^{\beta t}, & t \in [t_0, \infty), t_0 \geq 0, 0 < \alpha < 1, \\ y(t) &= \phi(t), & t_0 - h \leq t \leq t_0. \end{aligned} \tag{1}$$

Let $y \in C([t_0 - h, \infty), \mathbb{R})$. For every $t \in [t_0, \infty)$, define y_t by

$$y_t(\theta) = y(t + \theta), \quad \theta \in [-h, 0].$$

Denote by $BC([t_0 - h, \infty), \mathbb{R})$ the Banach space of all bounded continuous functions from $[t_0 - h, \infty)$ into \mathbb{R} with the norm $\|y\|_\infty = \sup\{|y(t)| : t \in [t_0 - h, \infty)\}$. Assume that $f(t, x_t)$ is Lebesgue measurable with respect to t on $[t_0, \infty)$, and $f(t_0, \phi)$ is continuous with respect to ϕ on $C([-h, 0], \mathbb{R})$. By the technique used in [1], we get the equivalent form of the equation (1) as

$$\begin{aligned} y(t) &= y(t_0)e^{-\beta(t-t_0)} + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} e^{-\beta(t-s)} f(s, y_s) ds, & t \geq t_0, \\ y(t) &= \phi(t), & t \in [t_0 - h, t_0]. \end{aligned} \tag{2}$$

The formal definition of the Hyers-Ulam-Rassias stability for the equation (2) can be defined as follows:

For each function y satisfying

$$\left| y(t) - y(t_0)e^{-\beta(t-t_0)} - \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} e^{-\beta(t-s)} f(s, y_s) ds \right| \leq \psi(t)$$

in which ψ is a nonnegative function, there is a solution y_0 of the equation (2) and a constant $K > 0$ independent of y and y_0 such that

$$|y(t) - y_0(t)| \leq K\psi(t).$$

In this talk we present some results on the stability of the equation (2).

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Ajda Fošner

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(joint work with **Maja Fošner**)

Some results on the stability of functional equations

A classical question in the theory of functional equations is: *Under what conditions is it true that a map which approximately satisfies a functional equation \mathcal{E} must be somehow close to an exact solution of \mathcal{E} ?* We say that a functional equation \mathcal{E} is stable if any approximate solution of \mathcal{E} is near to a true solution of \mathcal{E} . We will present some new results on the stability of functional equations. In particular, we will present the stability and hyperstability of cubic Lie derivations on normed algebras.

References

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Attila Gilányi

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On the stability of monomial functional equations

Let X and Y be linear normed spaces, and let n be a positive integer. A function $f: X \rightarrow Y$ is called a monomial function of degree n if it satisfies the functional equation

$$\Delta_y^n f(x) - n!f(y) = 0, \quad x, y \in X,$$

where Δ denotes the (forward) difference operator. It is well-known and easy to see that this class of equations contains the Cauchy equation and the square-norm (or parallelogram

or Jordan–von Neumann or quadratic) equation as a special case. The stability of equations belonging to the class have been investigated by several authors. In this talk, we give a short summary of their results and we present some conditional stability theorems for monomial equations.

Ioan Goleț

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(joint work with **Liviu Cădariu**)

Hyers-Ulam-Rassias stability in fuzzy normed spaces

The concept of fuzzy sets was introduced by Zadeh [5] in 1965. Since then, many authors have expansively developed the theory of fuzzy sets. Kramosil and Michalek [4] have introduced the concept of fuzzy metric spaces. George and Veeramani [1] modified this concept of fuzzy metric spaces and defined topologies induced by fuzzy metrics. Many authors have proved fixed point theorems in fuzzy metric spaces.

In the same time fuzzy norms have given appropriate generalizations of deterministic normed spaces and have opened the way for new applications.

Recently, considerable attention has given to the Hyers-Ulam-Rassias stability of functional or differential equations. This study is encouraged by the particular applications in the information theory, computer science etc. The fuzzy normed spaces has also offered a proper framework for the study of Hyers-Ulam-Rassias stability of some classical functional equations.

In this paper we use a fixed point result in fuzzy normed space as a tool for investigating the Hyers-Ulam-Rassias stability of a quadratic functional equation.

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Eszter Gselmann

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Characterization of derivations through their actions on certain elementary functions

The main aim of this talk is to provide characterization theorems concerning real derivations.

We say that an additive function $f: \mathbb{R} \rightarrow \mathbb{R}$ is a *derivation* if

$$f(xy) = xf(y) + yf(x)$$

is fulfilled for all $x, y \in \mathbb{R}$. The additive function $f: \mathbb{R} \rightarrow \mathbb{R}$ is termed to be a *linear function* if f is of the form

$$f(x) = f(1) \cdot x, \quad x \in \mathbb{R}.$$

This talk will be devoted to answering affirmatively the following problem in some cases. Assume that $\xi: \mathbb{R} \rightarrow \mathbb{R}$ is a given differentiable function and for the additive function $d: \mathbb{R} \rightarrow \mathbb{R}$, the mapping

$$x \longmapsto d(\xi(x)) - \xi'(x)d(x)$$

is regular (e.g. locally bounded, measurable, continuous at a point) on its domain. It is true that in case d admits a representation

$$d(x) = \chi(x) + d(1) \cdot x, \quad x \in \mathbb{R},$$

where $\chi: \mathbb{R} \rightarrow \mathbb{R}$ is a real derivation?

Eliza Jabłońska

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(joint work with **Janusz Brzdęk**)

Fixed points almost everywhere and Hyers-Ulam stability

In 2011 J. Brzdęk, J. Chudziak, Z. Páles [1] and J. Brzdęk, K. Ciepliński [2] proved fixed point theorems for some operators and derive from it several results on the stability of a very wide class of functional equations in single variable. In 2012 L. Cădariu, L. Găvruta, P. Găvruta [3] generalized these results.

Here we generalized results from [3]; more precisely, we prove a fixed point theorem almost everywhere and apply it to obtain some stability results.

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Wojciech Jabłoński

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Stability and completeness

Many authors examined stability of various functional equations since the time when S.M. Ulam [4] has posed his problem of stability of the equation of a homomorphism. We discuss these aspects of stability which concerns completeness of a target space (cf. [1], [2] and [3]).

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Zdeněk Kočan

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(joint work with **Veronika Kurková** and **Michal Málek**)

Dynamics on intervals, graphs and dendrites

Let us consider some properties of discrete dynamical systems such as the existence of an horseshoe, the positivity of topological entropy, the existence of a homoclinic trajectory or the existence of maximal omega-limit sets. We survey the known relations between the properties in the case of interval, graph and dendrite maps. In particular, we point out differences between the dynamics on intervals and on dendrites.

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Zbigniew Leśniak

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(joint work with **Janusz Brzdęk** and **Stevo Stević**)

On stability of an operator type equation of order n

We consider an n -th order linear operator type equation with constant coefficients

$$p_n \mathcal{L}^n \psi - p_{n-1} \mathcal{L}^{n-1} \psi + \dots + (-1)^{n-1} p_1 \mathcal{L} \psi + (-1)^n \psi = \theta,$$

where $\mathcal{L}: X \rightarrow X$, X is a complete extended normed vector space and θ is the zero of X . We show that, under suitable assumptions, the equation is stable in the Hyers-Ulam sense. To obtain this result we use the Diaz-Margolis fixed point theorem.

Renata Malejki

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(joint work with **Anna Bahyrycz**)

On stability of a generalization of the Fréchet equation

We present some stability and hyperstability results for the functional equation

$$A_1f(x + y + z) + A_2f(x) + A_3f(y) + A_4f(z) = A_5f(x + y) + A_6f(x + z) + A_7f(y + z),$$

which is a generalization of the Fréchet equation ($A_1 = \dots = A_7 = 1$) stemming from one of the characterizations of the inner product spaces. As the main tool in the proofs we have used a fixed point theorem for the function spaces.

Alpár Richárd Mészáros

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(joint work with **Szilárd András**)

Ulam-Hyers stability of elliptic PDEs in Sobolev spaces

In this talk we analyse the Ulam-Hyers stability of some elliptic partial differential equations on bounded domains with Lipschitz boundary. We use direct techniques and also some abstract methods of Picard operators.

The novelty of our approach consists in the fact that we are working in Sobolev spaces and we do not need to know the explicit solutions of the problems or the Green functions of the elliptic operators. We show that the Ulam-Hyers stability of linear elliptic problems do not say much information in plus, it mainly follows from standard estimations for elliptic PDEs, Cauchy-Schwartz and Poincaré type inequalities and Lax-Milgram type theorems.

We obtain powerful results in the sense that working in Sobolev spaces, we can control also the derivatives of the solutions, instead of the known point-wise stability for the moment (see [2]). Moreover our results for the nonlinear problems generalize in some sense some recent results from the literature (see for example [3]).

These results can be found in our recent paper [1].

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Second order non-linear ODEs with non-local initial conditions. Existence and Ulam-Hyers stability

In this talk our aim is to study some non-linear second order ODE systems with non-local initial conditions. The model problem is the following system

$$\begin{aligned}x''(t) &= -f_1(t, x(t), y(t)), & y''(t) &= -f_2(t, x(t), y(t)), & t \in I, \\x(0) &= \alpha_0[x], & x'(0) &= \alpha_1[x], & y(0) &= \beta_0[y], & y'(0) &= \beta_1[y],\end{aligned}$$

where $\alpha_i, \beta_i: \mathcal{C}[0, 1] \rightarrow \mathbb{R}$, $i \in \{0, 1\}$ are linear and continuous operators. In the model $I \subset \mathbb{R}$ is a bounded interval and $f_1, f_2: I \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are Carathéodory functions. Under certain assumptions on the data functions we are able to show existence of the solutions and Ulam-Hyers stability of the above system. For this analysis we use some fixed point techniques and the core of the approaches relies on vector valued metrics and converging to zero matrices. These techniques were first used for first order non-linear systems with non-local initial conditions (see [1, 2]) and the works [3, 4] motivate this type of study for second order cases.

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Strong convexity and separation theorems

Let $D \subset \mathbb{R}^n$ be a convex set and c be a positive number. A function $f: D \rightarrow \mathbb{R}$ is called:
– *strongly convex with modulus c* if

$$f(tx + (1-t)y) \leq tf(x) + (1-t)f(y) - ct(1-t)\|x - y\|^2, \quad x, y \in D, \quad t \in [0, 1];$$

– *approximately concave with modulus c* if

$$f(tx + (1-t)y) \geq tf(x) + (1-t)f(y) - ct(1-t)\|x - y\|^2, \quad x, y \in D, \quad t \in [0, 1];$$

– *c -quadratic* if

$$f(tx + (1-t)y) = tf(x) + (1-t)f(y) - ct(1-t)\|x - y\|^2, \quad x, y \in D, \quad t \in [0, 1].$$

A relationship between the above notions (for $n = 1$) and the generalized convexity in the sense of Beckenbach is shown. Characterizations of pairs of functions that can be separated by strongly convex, approximately concave and c -quadratic functions are given. As corollaries some Hyers-Ulam stability results for the above classes of functions are obtained.

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Andrzej Olbryś

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On separation by h -convex functions

Let X will be a real linear space, and let $D \subset X$ be an open and convex set. The concept of h -convexity was introduced by Varošanec [2] in the following way:

DEFINITION

Let $J \subset \mathbb{R}$ be an interval, $(0, 1) \subset J$ and let $h: J \rightarrow \mathbb{R}$ be a non-negative function. We say that $f: D \rightarrow \mathbb{R}$ is an h -convex function, if f is non-negative and for all $x, y \in D$ and $s \in (0, 1)$ we have

$$f(sx + (1 - s)y) \leq h(s)f(x) + h(1 - s)f(y).$$

In our talk we establish the necessary and sufficient conditions under which two functions can be separated by h -convex function, in the case, where the function h is supermultiplicative. This result is related to the theorem on separation by convex functions presented in [1]. As a consequence of our main theorem we obtain the stability result for h -convex functions.

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Jolanta Olko

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(joint work with **Anna Bahyrycz**)

On stability of the general linear equation

Consider the general linear functional equation of the form

$$\sum_{i=1}^m A_i f\left(\sum_{j=1}^n a_{ij}x_j\right) + A = 0,$$

where $A, a_{ij} \in \mathbb{F}$, $A_i \in \mathbb{F} \setminus \{0\}$, $i \in \{1, \dots, m\}$, $j \in \{1, \dots, n\}$ in the class of functions mapping a normed space into a Banach space (both over the same field \mathbb{R} or \mathbb{C}).

We give sufficient conditions for the generalized Hyers-Ulam stability of the equation. Moreover we present some applications to particular functional equations of this type and different control functions.

Lahbib Oubbi

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Ulam stability of an equation with several parameters

We deal with the Ulam-Hyers stability of the functional equation

$$\sum_{i=1}^m f(a_i x_0 + b_i x_i) + f\left(x_0 - \sum_{i=1}^m b_i x_i\right) - f(x_0) = 0, \quad (1)$$

where $m \geq 3$ is an integer, $(a_i)_{i=1, \dots, m}$ and $(b_i)_{i=1, \dots, m}$ are scalars so that $\sum_{i=1}^m a_i = 0$ and $b_i \neq 0$ for every $i = 1, \dots, m$. We first show that a mapping f satisfies (1) if and only if it is additive. We then show the Ulam-Hyers-Găvruta stability of the equation (1). Furthermore, using the classical fixed point theorem, we establish the Ulam-Hyers-Cădariu-Radu stability of (1). As corollary, we get the Ulam-Hyers-Rassias stability of (1). Finally, whenever the considered spaces are algebras, we combine (1) with some other equations such as $f(xy) = f(x)f(y)$ or $f(xy) = \alpha_1 x f(y) + \alpha_2 f(x)y$ and get the stability of different types of mappings (among which the ring derivations and the ring homomorphisms) with respect to the obtained systems of equations. The results obtained here are natural generalizations of the ones obtained in [1] and [2].

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Zsolt Páles

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Stability of generalized monomial functional equations

Given a groupoid (X, \diamond) , we define the powers of an element $x \in X$ by

$$x^1 := x, \quad x^{n+1} := x \diamond x^n, \quad n \in \mathbb{N}.$$

The groupoid as well as the operation \diamond is called power associative if, for all $x \in X$, for all $n, k \in \mathbb{N}$,

$$x^{n+k} = x^n \diamond x^k.$$

Given $\ell \geq 2$, the groupoid as well as the operation \diamond is said to be ℓ -power symmetric if, for all $x, y \in X$,

$$(x \diamond y)^\ell = x^\ell \diamond y^\ell.$$

Obviously, commutative semigroups are power associative and ℓ -power symmetric for every $\ell \geq 2$. On the other hand, there exist non-associative and non-commutative structures that are still power associative and 2-power symmetric.

The main result concerns the Hyers-Ulam stability of the generalized monomial functional equation

$$p_0 f(x) + p_1 f(x \diamond y) + \dots + p_n f(x \diamond y^n) = f(y), \quad x, y \in X,$$

where (G, \diamond) is a power associative and ℓ -power symmetric groupoid, $f: X \rightarrow Y$, Y is a Banach space over $\mathbb{K} \in \{\mathbb{R}, \mathbb{C}\}$ and $p_0, p_1, \dots, p_n \in \mathbb{K}$ with $p_0 + p_1 + \dots + p_n = 0$.

The particular case when $p_j = \frac{(-1)^{n-j}}{n!} \binom{n}{j}$ for $j \in \{0, 1, \dots, n\}$ is the standard monomial equation which was considered by A. Gilányi in 1999 in the paper [1].

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Paweł Pasteczka

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On negative results concerning Hardy means

A mean $M: \bigcup_{n=1}^{\infty} \mathbb{R}_+^n \rightarrow \mathbb{R}_+$ is called *Hardy* if there exists $C > 0$ such that $\sum_{n=1}^{\infty} M(a_1, \dots, a_n) < C \sum_{n=1}^{\infty} a_n$ for any sequence of arguments $a \in l^1(\mathbb{R}_+)$. We present some sufficient conditions for a mean *not* to be Hardy.

In 2004 Zs. Páles and L.-E. Persson [1] proved that a Gini Mean

$$G_{p,q}(a_1, \dots, a_n) := \begin{cases} \left(\frac{a_1^p + \dots + a_n^p}{a_1^q + \dots + a_n^q} \right)^{\frac{1}{p-q}}, & \text{if } p \neq q, \\ \exp \left(\frac{a_1^p \ln(a_1) + \dots + a_n^p \ln(a_n)}{a_1^p + \dots + a_n^p} \right), & \text{if } p = q \end{cases}$$

(i) is Hardy if $\max(p, q) < 1$ and $\min(p, q) \leq 0$,

(ii) is not Hardy if $\max(p, q) > 1$ or $\min(p, q) > 0$.

We are going to prove that the condition (i) is also a necessary one.

Moreover, we are going to precisely tell, in the family of Gaussian Product of Power Means, the Hardy means from the non-Hardy ones.

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Stability and hyperstability of the Drygas functional equation

Let X be a nonempty subset of an Abelian group and Y be a semigroup. We say that a function $f: X \rightarrow Y$ satisfies the Drygas functional equation on X if

$$f(x + y) + f(x - y) = 2f(x) + f(y) + f(-y)$$

for all $x, y \in X$ such that $-y, x + y, x - y \in X$.

We use the fixed point theorem for functional spaces to obtain the stability and hyperstability result for the Drygas functional equation on a restricted domain.

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(joint work with **Ioan Raşa**)

Hyers-Ulam stability of some equations and operators

We present some results concerning generalized Hyers-Ulam stability for the linear differential equation with constant coefficients and also for the linear differential operator with non-constant coefficients in Banach spaces. A characterization of Hyers-Ulam stability of linear operators in Banach spaces was given in [3].

Using this result we investigate the Hyers-Ulam (in)stability of some classical operators from approximation theory. For some of them we obtain the best constant.

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Barbara Przebieracz

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Stability of the translation equation

The aim of this talk is to present results concerning the stability of the translation equation in some classes of functions.

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Hyers-Ulam stability of an integro-differential equation

In [1], S.M. Jung applied the fixed point method for proving the Hyers-Ulam-Rassias stability and the Hyers-Ulam stability of a Volterra integral equation of the second kind. In [2], Morales and Rojas studied the Hyers-Ulam-Rassias types of stability of nonlinear, nonhomogeneous Volterra integral equations with delay on finite intervals. Recently in [3], Jung, Şevgin and Şevli proved that if $p: I \rightarrow \mathbb{R}$, $q: I \rightarrow \mathbb{R}$, $K: I \times I \rightarrow \mathbb{R}$ and $\varphi: I \rightarrow [0, \infty)$ are sufficiently smooth functions and if a continuously differentiable function $u: I \rightarrow \mathbb{R}$ satisfies the perturbed Volterra integro-differential equation

$$\left| u'(t) + p(t)u(t) + q(t) + \int_c^t K(t, \tau)u(\tau) d\tau \right| \leq \varphi(t)$$

for all $t \in I$, then there exists a unique solution $u_0: I \rightarrow \mathbb{R}$ of the Volterra integro-differential equation $u'(t) + p(t)u(t) + q(t) + \int_c^t K(t, \tau)u(\tau) d\tau = 0$ such that

$$|u(t) - u_0(t)| \leq \exp \left\{ - \int_c^t p(\tau) d\tau \right\} \int_t^b \varphi(\xi) \exp \left\{ \int_c^\xi p(\tau) d\tau \right\} d\xi$$

for all $t \in I$.

In this study, we will establish the Hyers-Ulam-Rassias stability and the Hyers-Ulam stability of a integro-differential equation.

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Hyers-Ulam stability of Volterra integro-differential equations

Let I be either $(-\infty, b]$, \mathbb{R} , $[a, \infty)$, or a closed interval $[a, b]$ with $-\infty < a < b < \infty$, let c be a fixed point of I , and let $\varphi: I \rightarrow [0, \infty)$ be a continuous function. S.M. Jung [1] proved that if a continuous function $u: I \rightarrow \mathbb{C}$ satisfies the perturbed Volterra integral equation of second kind

$$\left| u(t) - \int_c^t F(\tau, u(\tau)) d\tau \right| \leq \varphi(t)$$

for all $t \in I$, then under some additional conditions, there exist a unique continuous function $u_0: I \rightarrow \mathbb{C}$ and a constant $C > 0$ such that

$$u_0(t) = \int_c^t F(\tau, u_0(\tau)) d\tau \quad \text{and} \quad |u(t) - u_0(t)| \leq C\varphi(t)$$

for all $t \in I$. Recently in [2] the authors jointly with S.M. Jung proved that if $p: I \rightarrow \mathbb{R}$, $q: I \rightarrow \mathbb{R}$, $K: I \times I \rightarrow \mathbb{R}$ and $\varphi: I \rightarrow [0, \infty)$ are sufficiently smooth functions and if a continuously differentiable function $u: I \rightarrow \mathbb{R}$ satisfies the perturbed Volterra integro-differential equation

$$\left| u'(t) + p(t)u(t) + q(t) + \int_c^t K(t, \tau)u(\tau) d\tau \right| \leq \varphi(t)$$

for all $t \in I$, then there exists a unique solution $u_0: I \rightarrow \mathbb{R}$ of the Volterra integro-differential equation

$$u'(t) + p(t)u(t) + q(t) + \int_c^t K(t, \tau)u(\tau) d\tau = 0$$

such that

$$|u(t) - u_0(t)| \leq \exp \left\{ - \int_c^t p(\tau) d\tau \right\} \int_t^b \varphi(\xi) \exp \left\{ \int_c^\xi p(\tau) d\tau \right\} d\xi$$

for all $t \in I$.

In this paper, we will apply the fixed point method for proving the Hyers-Ulam-Rassias stability and the Hyers-Ulam stability of a nonlinear Volterra integro-differential equation.

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Stanisław Siudut

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Cauchy difference operator in some Orlicz classes

Let (G, \cdot, λ) be a measurable group with a complete, left-invariant and finite measure λ . If φ is a convex φ -function satisfying conditions $\frac{\varphi(u)}{u} \rightarrow 0$ as $u \rightarrow 0$, $\frac{\varphi(u)}{u} \rightarrow \infty$ as $u \rightarrow \infty$, $f: G \rightarrow \mathbb{R}$ and the Cauchy difference $\mathcal{C}f(x, y) = f(x \cdot y) - f(x) - f(y)$ of f belongs to $\mathcal{L}_{\lambda \times \lambda}^{\varphi}(G \times G, \mathbb{R})$, then there exists unique additive $A: G \rightarrow \mathbb{R}$ such that $f - A \in \mathcal{L}_{\lambda}^{\varphi}(G, \mathbb{R})$. Moreover, $\|f - A\|_{\varphi} \leq K\|\mathcal{C}f\|_{\varphi}$, where $K = 1$ if $\lambda(G) \geq 1$, $K = 1 + (\lambda(G))^{-1}$ if $\lambda(G) < 1$. Similar result we also obtain without associativity of \cdot but with $f \in \mathcal{L}_{\lambda}^{\varphi}(G, \mathbb{R})$ and with measurability of $\mathcal{C}f$. In this case $A = 0$ and the Cauchy difference $\mathcal{C}: \{f \in L_{\lambda}^{\varphi}(G, \mathbb{R}) \mid \mathcal{C}f \in L_{\lambda \times \lambda}^{\varphi}(G \times G, \mathbb{R})\} \rightarrow L_{\lambda \times \lambda}^{\varphi}(G \times G, \mathbb{R})$ is linear continuous and continuously invertible on its image, where $L_{\lambda}^{\varphi}(G, \mathbb{R})$ ($L_{\lambda \times \lambda}^{\varphi}(G \times G, \mathbb{R})$) denotes the space of equivalence classes of functions in $\mathcal{L}_{\lambda}^{\varphi}(G, \mathbb{R})$ ($\mathcal{L}_{\lambda \times \lambda}^{\varphi}(G \times G, \mathbb{R})$). Moreover, \mathcal{C} is compact if and only if the domain of \mathcal{C} has a finite dimension.

Let (G, \cdot, λ) be a measurable group with a complete, left-invariant and σ -finite measure λ such that $\lambda(G) = \infty$. If φ is a φ -function, $f: G \rightarrow \mathbb{R}$ and $\mathcal{C}f \in \mathcal{L}_{\lambda}^{\varphi}(G \times G, \mathbb{R})$, then there exist a unique additive $A: G \rightarrow \mathbb{R}$ which is equal to f λ a.e.

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(joint work with **Szymon Wąsowicz**)

Symmetrization and convexity II

In Sz. Wąsowicz's talk the symmetrization method was presented. We use it to prove the Hermite–Hadamard type inequalities for Wright-convex, strongly convex and strongly Wright-convex functions of several variables defined on simplices.

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Distributional chaos after twenty years

Twenty years ago, in [1] there was introduced the notion of distributional chaos for continuous maps of the interval. The notion was later generalized in [2] and [3] to continuous maps of a compact metric space. There appeared many open problems, some of them were already solved. The most important recent result is a proof of the conjecture, that positive topological entropy implies distributional chaos DC2. In the talk we provide a brief survey of history, main properties of distributional chaos, main open problems, and possible directions of other research of the field.

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On the Sharkovsky classification program of triangular maps

For continuous interval maps there are more than 50 mutually equivalent conditions characterizing maps with zero topological entropy. At the end of the 1980s Sharkovsky proposed to verify which of the implications between these conditions are valid in the class of triangular maps of the unit square. Since some conditions are not applicable to maps of the square whereas some new conditions have been added thereafter the contemporary list usually contains 32 conditions which means nearly 1000 possible implications. This huge program has been recently completed and in my talk I will give a survey of these results with emphasis on the most recent ones.

Stevo Stević

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Unique existence of solutions of a class of nonlinear functional equations in a neighborhood of zero

We present a unique existence result for a solution of the following system of nonlinear functional equations with iterated deviations in a neighborhood of zero and satisfying the Lipschitz condition

$$x(t) = f(t, x(v_1^{(1)}(t, x)), \dots, x(v_1^{(k)}(t, x))),$$

where

$$v_j^{(i)}(t, x) = \alpha_{ij}t + \varphi_{ij}(t, x(\alpha_{i,j+1}t + \varphi_{i,j+1}(\dots x(\alpha_{i,m_i}t + \varphi_{i,m_i}(t, x(t))\dots)))$$

$\alpha_{ij} \in \mathbb{R}$, $i = \overline{1, k}$, $j = \overline{1, m_i}$, $\varphi_{ij}(t, x)$, $i = \overline{1, k}$, $j = \overline{1, m_i}$, are real functions, $f(t, x_1, \dots, x_k)$ is a real vector function satisfying some additional conditions, and $x(t)$ is an unknown vector function on a subset of \mathbb{R}^N .

Leszek Szala

Silesian University in Opava, Opava, Czech Republic

Chaotic behavior of discrete dynamical systems with randomly perturbed trajectories

My talk will concern recurrence for discrete dynamical systems defined on the unit interval I or on the cube I^n with randomly perturbed trajectories. Both autonomous and nonautonomous case will be concerned. A review of known results as well as some of my recent ones, showing relations between classical recurrence (i.e. for systems without random perturbations) and the so called (f, δ) -recurrence will be presented.

References

- [1] K. Janková, J. Smítal, *Maps with random perturbations are generically not chaotic*, Internat. J. Bifur. Chaos Appl. Sci. Engrg. **5** (1995), 1375–1378.
- [2] L. Szala, *Recurrence in systems with random perturbations*, Internat. J. Bifur. Chaos Appl. Sci. Engrg. **23** (2013), 1350110, 5pp.

Joanna Szczawińska

Pedagogical University, Kraków, Poland
(joint work with **Andrzej Smajdor**)

Selections of generalized convex set-valued functions with bounded diameter

Let $\alpha \in (-1, 1)$, $p, q > 0$, K be a subset of a vector space X such that $0 \in K$ and $K \subset pK$ and let $(Y, \|\cdot\|)$ be a real Banach space. Consider a set-valued function $F: K \rightarrow cl(Y)$ satisfying the following conditional inclusion

$$\alpha F(x) + (1 - \alpha)F(y) \subset F(px + qy), \quad x, y \in K, \quad px + qy \in K.$$

We prove that if the set-valued function F has a bounded diameter, i.e.

$$\sup\{\text{diam}F(x), x \in K\} = M < +\infty,$$

then there exists a unique function $f: K \rightarrow Y$ such that

$$\alpha f(x) + (1 - \alpha)f(y) = f(px + qy), \quad x, y \in K, \quad px + qy \in K$$

and

$$f(x) + F(0) \subset F(x), \quad x \in K.$$

We also apply the method used in the proof to the investigation of the stability of the functional equation

$$\alpha f(x) + (1 - \alpha)f(y) = f(px + qy).$$

László Székelyhidi

University of Debrecen, Debrecen, Hungary

Stability of functional equations on hypergroups

In this talk we present stability results for diverse functional equations on hypergroups. The functional equations involved characterize exponentials, additive functions and moment functions. We also consider equations of mixed type. The results depend on amenability and superstability, as well as on a combination of these properties.

Tomasz Szostok

University of Silesia, Katowice, Poland

Stability of functional equations stemming from numerical analysis

We study the stability properties of the equation

$$F(y) - F(x) = (y - x) \sum_{i=1}^n a_i f(\alpha_i x + \beta_i y) \tag{1}$$

which is motivated by the numerical integration. In [1] the stability of the simplest equation of the type (1) was investigated thus the inequality

$$|F(y) - F(x) - (y - x)f(x + y)| \leq \varepsilon$$

was studied. In the current paper we present a somewhat different approach to the problem of stability of (1). Namely, we deal with the inequality

$$\left| \frac{F(y) - F(x)}{y - x} - \sum_{i=1}^n a_i f(\alpha_i x + \beta_i y) \right| \leq \varepsilon.$$

References

- [1] T. Szostok, Sz. Wąsowicz, *On the stability of the equation stemming from Lagrange MVT*, Appl. Math. Lett. **24** (2011), 541–544.

Jacek Tabor

Jagiellonian University, Kraków, Poland
(joint work with **Józef Tabor** and **Ewa Matczyńska**)

Stability of the elastic maps

In our talk we study the stability of the *elastic maps*. Roughly speaking [1], a function $e: \{-n, \dots, n\} \times \{-k, \dots, k\} \rightarrow \mathbb{R}^d$ is called an elastic map if it approximately satisfies the Jensen condition

$$e\left(\frac{p+q}{2}\right) = \frac{e(p) + e(q)}{2}$$

for $p, q, \frac{p+q}{2} \in \text{dom}(e)$ such that $(p, q) \in N(\mathbb{Z}^2)$ where $N(\mathbb{Z}^2)$ denotes the set of neighbors in \mathbb{Z}^2 , that is points such that $\|p - q\|_{\max} \leq 2$. We also discuss the case when the set of neighbors is exchanged with its subset.

References

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Szymon Wąsowicz

University of Bielsko-Biała, Bielsko-Biała, Poland
(joint work with **Alfred Witkowski**)

Symmetrization and convexity I

It is well-known that the Hermite part of the Hermite–Hadamard inequality estimates the integral mean value of a convex function of one real variable better than the Hadamard part. Unfortunately, this is not the case in the multivariate case. Nevertheless, it is possible to give a refinement going in this spirit. The presented result we prove by using the symmetrization method.

References

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Paweł Wójcik

Pedagogical University, Kraków, Poland

On a restriction of an operator to an invariant subspace

For Banach spaces we consider the bounded linear operators which are surjective and noninjective. The aim of this report is to discuss an invariant subspace of some surjective operators. We show some general properties of such mappings. We examine whether such operators can restrict to an involution or a projection. Thus, we will obtain the invariant subspaces for those operators.

References

- [1] J.B. Conway, *A Course in Functional Analysis*, Springer–Verlag New York, 1985.
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Peter Volkmann
KIT, Karlsruhe, Germany

Bounded perturbations of additive functions

The topic will be discussed within the scope of Pólya-Szegő-Hyers-Ulam stability.

Pavol Zlatoš
Comenius University, Bratislava, Slovakia

Stability of homomorphisms in the compact-open topology

It seems that so far stability of homomorphisms between topological groups was studied exclusively from the global point of view, related to the topology of uniform convergence, dealing with approximability of everywhere defined maps by continuous homomorphisms. We introduce a local notion of stability, related to the compact-open topology, dealing with approximate extendability of partial maps to continuous homomorphisms.

We prove that the characters of any locally compact abelian group are locally stable in this sense. We also generalize a global stability result on continuous homomorphisms between compact groups to a local version for continuous homomorphisms from any locally compact group to an arbitrary topological group and show the necessity of the assumptions of the theorem through some counterexamples. As an application we obtain a purely algebraic result on extendability of finite partial maps to homomorphisms.

Some of these results can be generalized to homomorphisms between topological universal algebras. By means of Nonstandard Analysis some of them can be strengthened, adding them certain kind of uniformity.

References

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